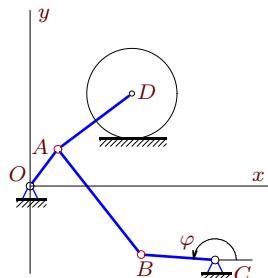


## Кинематический анализ плоского механизма (2)

Механизм изображен в произвольном положении, определяемом некоторым углом  $\varphi$ . Задана угловая скорость одного из звеньев или скорость центра диска. Длины звеньев даны в сантиметрах, радиус диска равен 5 см. Заданы координаты шарнира  $C$  и ордината оси диска в осях с началом в шарнире  $O$ . Диск катится без проскальзывания. Найти угловые скорости всех звеньев механизма и скорость центра диска (если она не задана) при  $\varphi = \varphi_0$ .

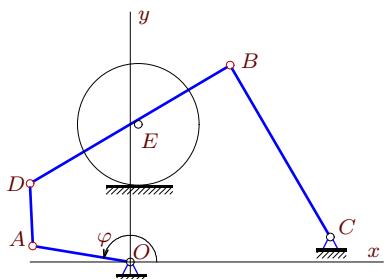
**Кирсанов М.Н. Решебник. Теоретическая механика/Под ред. А. И. Кириллова.– М.: ФИЗМАТЛИТ, 2008. – 384 с. (с.158.)**

### Задача 27.1.



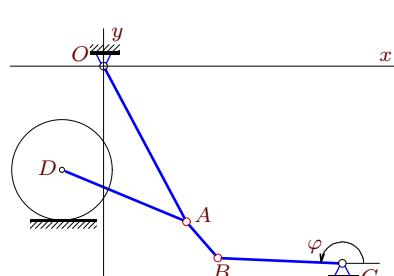
$$\omega_{OA_z} = 24 \text{ рад/с}, OA = 5, AB = 15, BC = 8, AD = 10, x_C = 20, y_C = -8, y_D = 10, \varphi_0 = \pi.$$

### Задача 27.3.



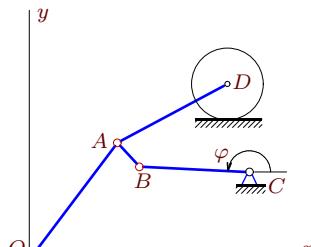
$$v_{Ex} = -105 \text{ см/с}, BC=17, DE = BE = 10, OA = 8, AD = 5, x_C = 16, y_C = 2, y_E = 11, \varphi_0 = \pi.$$

### Задача 27.5.



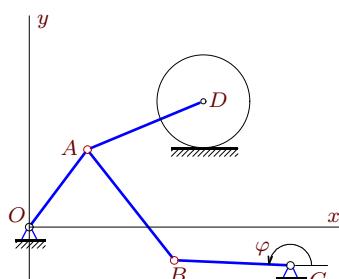
$$\omega_{BC_z} = -13 \text{ рад/с}, OA = 17, AB = 5, BC = 12, AD = 13, x_C = 23, y_C = -19, y_D = -10, \varphi_0 = \pi.$$

### Задача 27.2.



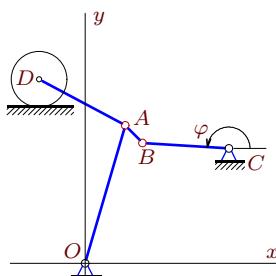
$$\omega_{BC_z} = -8 \text{ рад/с}, OA = 20, AB = 5, BC = 15, AD = 17, x_C = 30, y_C = 12, y_D = 24, \varphi_0 = \pi.$$

### Задача 27.4.

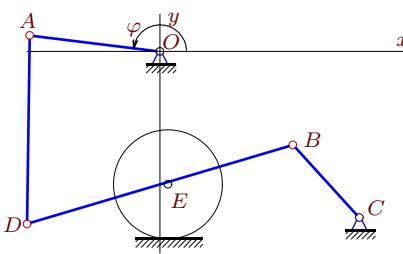


$$\omega_{OA_z} = 6 \text{ рад/с}, OA = 10, AB = 15, BC = 12, AD = 13, x_C = 27, y_C = -4, y_D = 13, \varphi_0 = \pi.$$

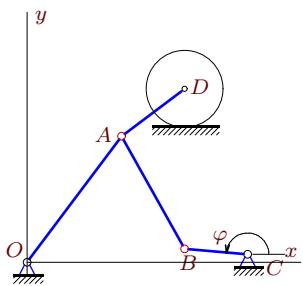
### Задача 27.6.



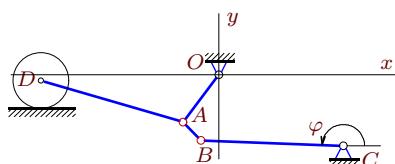
$$v_{Dx} = -416 \text{ см/с}, OA = 25, AB = 5, BC = 15, AD = 17, x_C = 25, y_C = 20, y_D = 32, \varphi_0 = \pi.$$

**Задача 27.7.**

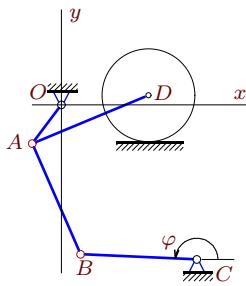
$\omega_{BCz} = 34 \text{ рад/с}$ ,  $BC = 10$ ,  
 $DE = BE = 13$ ,  $OA = 12$ ,  
 $AD = 17$ ,  $x_C = 18$ ,  $y_C = -15$ ,  
 $y_E = -12$ ,  $\varphi_0 = \pi$ .

**Задача 27.9.**

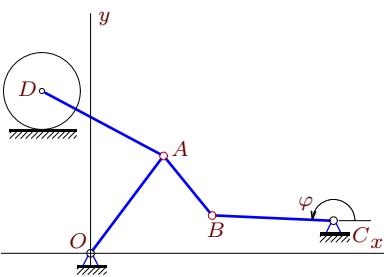
$v_{Dx} = 210 \text{ см/с}$ ,  $OA = 20$ ,  
 $AB = 17$ ,  $BC = 8$ ,  $AD = 10$ ,  
 $x_C = 28$ ,  $y_C = 1$ ,  $y_D = 22$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.11.**

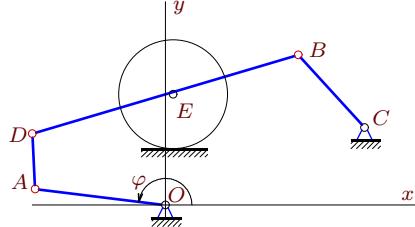
$\omega_{BCz} = -2 \text{ рад/с}$ ,  $OA = 10$ ,  
 $AB = 5$ ,  $BC = 24$ ,  $AD = 25$ ,  
 $x_C = 21$ ,  $y_C = -12$ ,  $y_D = -1$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.8.**

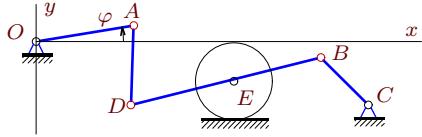
$\omega_{BCz} = 14 \text{ рад/с}$ ,  $OA = 5$ ,  
 $AB = 13$ ,  $BC = 12$ ,  $AD = 13$ ,  
 $x_C = 14$ ,  $y_C = -16$ ,  $y_D = 1$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.10.**

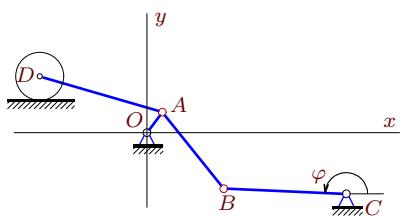
$\omega_{OAz} = -10 \text{ рад/с}$ ,  $OA = 15$ ,  
 $AB = 10$ ,  $BC = 15$ ,  $AD = 17$ ,  
 $x_C = 30$ ,  $y_C = 4$ ,  $y_D = 20$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.12.**

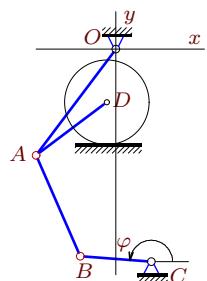
$v_{Ex} = -105 \text{ см/с}$ ,  $BC = 10$ ,  
 $DE = BE = 13$ ,  $OA = 12$ ,  
 $AD = 5$ ,  $x_C = 18$ ,  $y_C = 7$ ,  
 $y_E = 10$ ,  $\varphi_0 = \pi$ .

**Задача 27.13.**

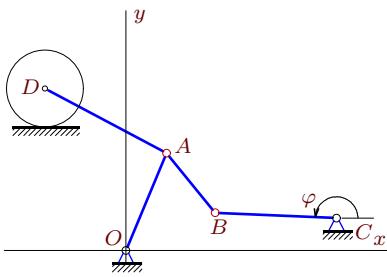
$\omega_{OA_z} = 5 \text{ рад/с}$ ,  $BC = 10$ ,  
 $DE = BE = 13$ ,  $OA = 12$ ,  
 $AD = 10$ ,  $x_C = 42$ ,  $y_C = -8$ ,  
 $y_E = -5$ ,  $\varphi_0 = 0$ .

**Задача 27.15.**

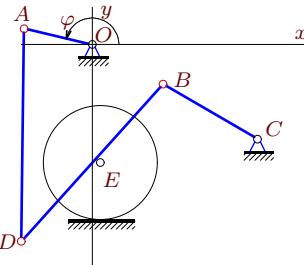
$v_{Dx} = -39 \text{ см/с}$ ,  $OA = 5$ ,  
 $AB = 20$ ,  $BC = 24$ ,  $AD = 25$ ,  
 $x_C = 39$ ,  $y_C = -12$ ,  $y_D = 11$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.17.**

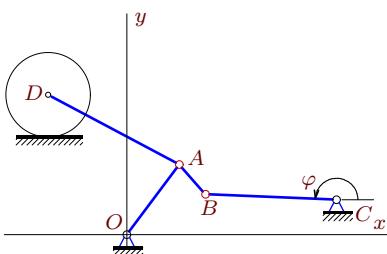
$\omega_{BC_z} = 14 \text{ рад/с}$ ,  $OA = 15$ ,  
 $AB = 13$ ,  $BC = 8$ ,  $AD = 10$ ,  
 $x_C = 4$ ,  $y_C = -24$ ,  $y_D = -6$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.14.**

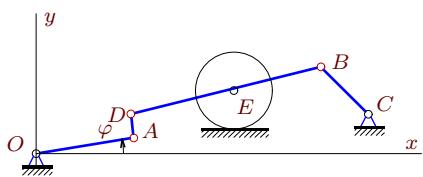
$\omega_{BC_z} = 28 \text{ рад/с}$ ,  $OA = 13$ ,  
 $AB = 10$ ,  $BC = 15$ ,  $AD = 17$ ,  
 $x_C = 26$ ,  $y_C = 4$ ,  $y_D = 20$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.16.**

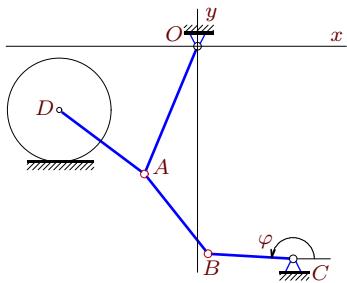
$\omega_{BC_z} = 27 \text{ рад/с}$ ,  $BC = 10$ ,  
 $DE = BE = 10$ ,  $OA = 6$ ,  
 $AD = 18$ ,  $x_C = 14$ ,  $y_C = -8$ ,  
 $y_E = -10$ ,  $\varphi_0 = \pi$ .

**Задача 27.18.**

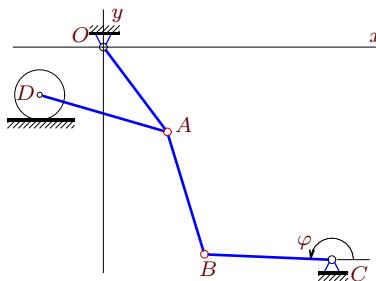
$v_{Dx} = -56 \text{ см/с}$ ,  $OA = 10$ ,  
 $AB = 5$ ,  $BC = 15$ ,  $AD = 17$ ,  
 $x_C = 24$ ,  $y_C = 4$ ,  $y_D = 16$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.19.**

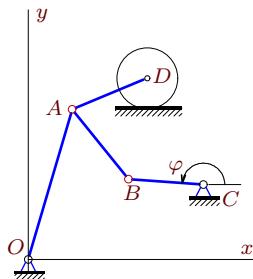
$\omega_{OA_z} = 3 \text{ рад/с}$ ,  $BC = 10$ ,  
 $DE = BE = 13$ ,  $OA = 12$ ,  
 $AD = 3$ ,  $x_C = 42$ ,  $y_C = 5$ ,  
 $y_E = 8$ ,  $\varphi_0 = 0$ .

**Задача 27.21.**

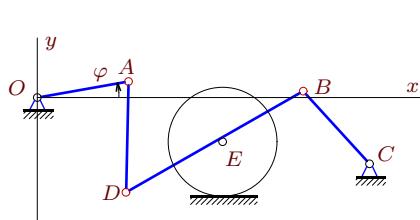
$v_{Dx} = 126 \text{ см/с}$ ,  $OA = 13$ ,  
 $AB = 10$ ,  $BC = 8$ ,  $AD = 10$ ,  
 $x_C = 9$ ,  $y_C = -20$ ,  $y_D = -6$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.23.**

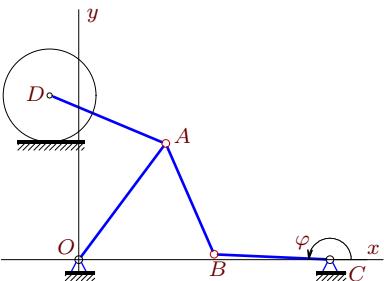
$v_{Dx} = -189 \text{ см/с}$ ,  $OA = 15$ ,  
 $AB = 13$ ,  $BC = 12$ ,  $AD = 13$ ,  
 $x_C = 26$ ,  $y_C = 0$ ,  $y_D = 17$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.20.**

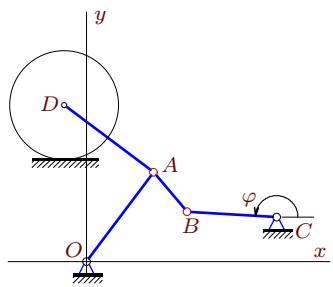
$\omega_{BC_z} = -25 \text{ рад/с}$ ,  $OA = 25$ ,  
 $AB = 15$ ,  $BC = 12$ ,  $AD = 13$ ,  
 $x_C = 28$ ,  $y_C = 12$ ,  $y_D = 29$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.22.**

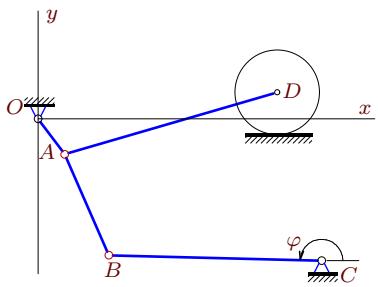
$\omega_{BC_z} = 20 \text{ рад/с}$ ,  $BC = 10$ ,  
 $DE = BE = 10$ ,  $OA = 8$ ,  
 $AD = 10$ ,  $x_C = 30$ ,  $y_C = -6$ ,  
 $y_E = -4$ ,  $\varphi_0 = 0$ .

**Задача 27.24.**

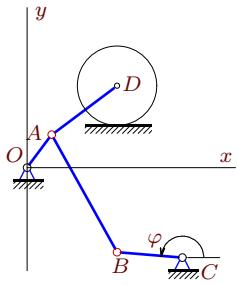
$v_{Dx} = -189 \text{ см/с}$ ,  $OA = 15$ ,  
 $AB = 13$ ,  $BC = 12$ ,  $AD = 13$ ,  
 $x_C = 26$ ,  $y_C = 0$ ,  $y_D = 17$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.25.**

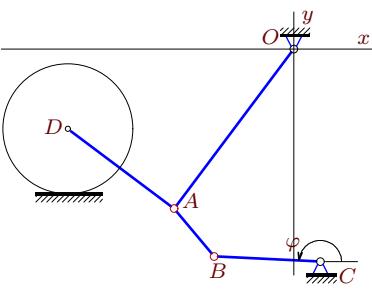
$\omega_{OA_z} = -4 \text{ рад/с}$ ,  $OA = 10$ ,  
 $AB = 5$ ,  $BC = 8$ ,  $AD = 10$ ,  
 $x_C = 17$ ,  $y_C = 4$ ,  $y_D = 14$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.27.**

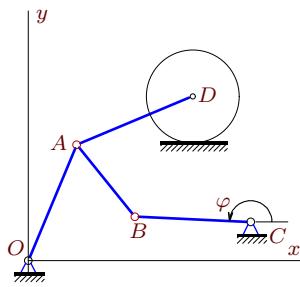
$v_{Dx} = -351 \text{ см/с}$ ,  $OA = 5$ ,  
 $AB = 13$ ,  $BC = 24$ ,  $AD = 25$ ,  
 $x_C = 32$ ,  $y_C = -16$ ,  $y_D = 3$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.29.**

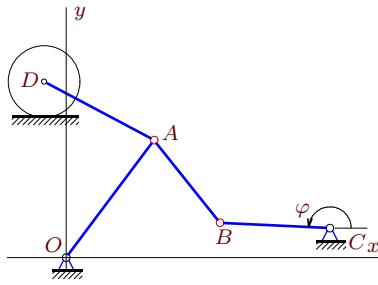
$\omega_{BC_z} = -77 \text{ рад/с}$ ,  $OA = 5$ ,  
 $AB = 17$ ,  $BC = 8$ ,  $AD = 10$ ,  
 $x_C = 19$ ,  $y_C = -11$ ,  $y_D = 10$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.26.**

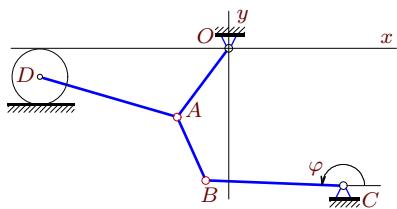
$\omega_{BC_z} = -18 \text{ рад/с}$ ,  $OA = 15$ ,  
 $AB = 5$ ,  $BC = 8$ ,  $AD = 10$ ,  
 $x_C = 2$ ,  $y_C = -16$ ,  $y_D = -6$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.28.**

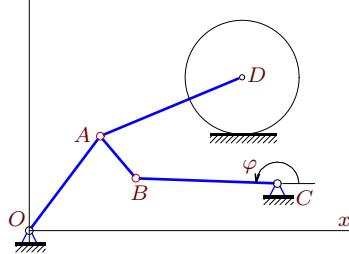
$\omega_{OA_z} = 12 \text{ рад/с}$ ,  $OA = 13$ ,  
 $AB = 10$ ,  $BC = 12$ ,  $AD = 13$ ,  
 $x_C = 23$ ,  $y_C = 4$ ,  $y_D = 17$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.30.**

$v_{Dx} = -336 \text{ см/с}$ ,  $OA = 20$ ,  
 $AB = 15$ ,  $BC = 15$ ,  $AD = 17$ ,  
 $x_C = 36$ ,  $y_C = 4$ ,  $y_D = 24$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.31.**

$\omega_{OA_z} = -24$  рад/с,  $OA = 15$ ,  
 $AB = 13$ ,  $BC = 24$ ,  $AD = 25$ ,  
 $x_C = 20$ ,  $y_C = -24$ ,  $y_D = -5$ ,  
 $\varphi_0 = \pi$ .

**Задача 27.32.**

$\omega_{BC_z} = -2$  рад/с,  $OA = 10$ ,  
 $AB = 5$ ,  $BC = 12$ ,  $AD = 13$ ,  
 $x_C = 21$ ,  $y_C = 4$ ,  $y_D = 13$ ,  
 $\varphi_0 = \pi$ .

**Кинематический анализ плоского механизма (2)**

№	$\omega_{OA_z}$	$\omega_{AB_z}$	$\omega_{BC_z}$	$\omega_{AD_z}$	$\omega_{BD_z}$	$v_{Dx}$	$v_{Ex}$
1	-	8	-18	-9	-	42	-
2	5	20	-	-4	-	48	-
3	-5	-	5	27	-5	-	-
4	-	4	-6	-3	-	33	-
5	-48	180	-	-32	-	560	-
6	-15	-90	25	-7	-	-	-
7	-17	-	-	-26	-17	-	-357
8	36	-12	-	9	-	-99	-
9	30	32	-77	-45	-	-	-
10	-	-15	12	-6	-	-168	-
11	-4	8	-	1	-	39	-
12	-5	-	10	26	-5	-	-
13	-	-	10	-13	-5	-	-105
14	-30	-45	-	-10	-	-440	-
15	-8	-2	2	-1	-	-	-
16	-36	-	-	-41	-36	-	-450
17	8	-8	-	9	-	-42	-
18	-5	-10	4	-2	-	-	-
19	-	-	6	26	-3	-	-63
20	12	24	-	-7	-	253	-
21	-8	12	-14	5	-	-	-
22	15	-	-	-34	-15	-	-250
23	-36	24	-	-18	-	450	-
24	-12	-12	14	-9	-	-	-
25	-	-8	6	-3	-	-50	-
26	-8	24	-	9	-	150	-
27	72	-24	-4	-9	-	-	-
28	-	18	-14	-5	-	119	-
29	120	32	-	-45	-	210	-
30	-15	-20	24	-12	-	-	-
31	-	24	-14	9	-	351	-
32	2	4	-	-1	-	11	-